

**WHAT IS CLAIMED IS :**

1. A method for controlling the functioning of a tire, comprising the step of:
  - (a) determining estimations or measurements of the slip  $G_i$  and the coefficient of friction  $\mu_i$  prevailing at said slip, for at least one pair "i" of values ( $G_i, \mu_i$ ) in a coordinate system having an axis  $G$ , an axis  $\mu$  and an origin;
  - (b) determining the value of the slope  $\alpha_i$  of the straight line passing through the origin and through each pair of values ( $G_i, \mu_i$ );
  - (c) calculating a coefficient  $B$  by direct calculation or by a regression from a sufficient number of pairs of ( $\alpha_i, G_i$ ) so as to estimate the value of slope  $\alpha_0$  at the origin; and
  - (d) using  $\alpha_0$  in an indicator of the longitudinal stiffness of the tread pattern.
2. A method for controlling the functioning of a tire according to Claim

1, in which the slope  $\alpha_i$  is determined by direct calculation  $\alpha_i = \mu_i / G_i$ .

3. A method for controlling the functioning of a tire according to Claim 1, in which the slope  $\alpha_i$  is determined by carrying out a suitable regression.

4. A method for controlling the functioning of a tire according to Claim 1, in which the following linear regression is carried out:

$$\Sigma_{GG} = \Sigma G_j^2, \Sigma_{G\mu} = \Sigma G_j \cdot \mu_j, \alpha_i = \frac{\Sigma_{G\mu}}{\Sigma_{GG}}$$

5. A method for controlling the functioning of a tire according to Claim 1, in which a coefficient  $B$ , representative of the longitudinal stiffness, is calculated by the following linear regression, applied to "n" measured or estimated points:

$$B^{Lin} = \frac{\Sigma \alpha \cdot \Sigma G^2 - \Sigma G \cdot \alpha \cdot \Sigma G}{n \cdot \Sigma G^2 - (\Sigma G)^2}$$

6. A method for controlling the functioning of a tire according to Claim 1, in which the coefficient B, representative of the longitudinal stiffness, is calculated by the following exponential regression, applied to “n” measured or estimated points:

$$B^{Exp} = \frac{\sum \ln(\alpha) \cdot \sum G^2 - \sum G \cdot \ln(\alpha) \cdot \sum G}{n \cdot \sum G^2 - (\sum G)^2}$$

7. A method for controlling the functioning of a tire according to Claim 1, in which an average value of  $\alpha_0$  is determined and a comparison with reference values for the tire subject to processing is made, in order to estimate the wear rate.

8. A method for controlling the functioning of a tire according to Claim 7, wherein an estimation of the remaining height H of the tread pattern is made as follows:

$$H = H_0 \cdot \frac{Stiffness}{Stiffness_0}$$

9. A method for controlling the functioning of a tire according to Claim 7 or 8, in which an average value of  $\alpha_0$  is determined on the basis of a predetermined number of brakings or accelerations.

10. A method for controlling the functioning of a tire according to Claim 7 or 8, in which an average value of  $\alpha_0$  is determined on the basis of a predetermined distance.